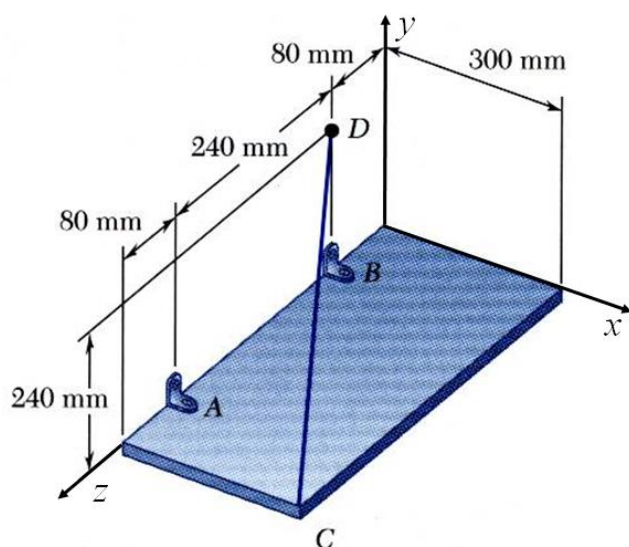


一矩形板由  $A$  與  $B$  兩處的拖架以及一線材  $CD$  支撐。已知線材施加一張力於點  $C$ ，此張力可表示為向量  $\mathbf{P} = P \mathbf{e} = P_x \mathbf{i} + P_y \mathbf{j} + P_z \mathbf{k}$ ，其大小  $P$  為 200 N。粗體符號表示向量、斜體符號表示純量。其中  $\mathbf{i} = (1, 0, 0)$ ， $\mathbf{j} = (0, 1, 0)$ ， $\mathbf{k} = (0, 0, 1)$  分別為指向正  $x$ 、 $y$  和  $z$  軸的單位向量。 $\mathbf{e}$  為沿  $CD$  的單位向量， $|\mathbf{e}| = 1$ 。

- (3%) 試以  $\mathbf{i}$ 、 $\mathbf{j}$ 、 $\mathbf{k}$  表示  $\mathbf{e}$ 。
- (2%) 試求  $P_x$ 、 $P_y$  和  $P_z$ 。
- (5%) 試求  $\mathbf{P}$  對點  $A$  的力矩  $\mathbf{M}_A$ 。
- (5%) 若  $AB$  為固定軸，矩形板可繞  $AB$  旋轉， $\mathbf{P}$  對  $AB$  的力矩為  $M_{AB} \mathbf{k}$ 。試求  $M_{AB}$ 。(提示：若一力平行於轉軸，則此力對轉軸的力矩為零。)
- (5%) 試求  $AB$  與  $CD$  的垂直距離。



## 参考解答

**STRATEGY:** The solution requires resolving the tension in the wire and the position vector from  $A$  to  $C$  into rectangular components. You will need a unit vector approach to determine the force components.

**MODELING and ANALYSIS:** Obtain the moment  $\mathbf{M}_A$  about  $A$  of the force  $\mathbf{F}$  exerted by the wire on point  $C$  by forming the vector product

$$\mathbf{M}_A = \mathbf{r}_{C/A} \times \mathbf{F} \quad (1)$$

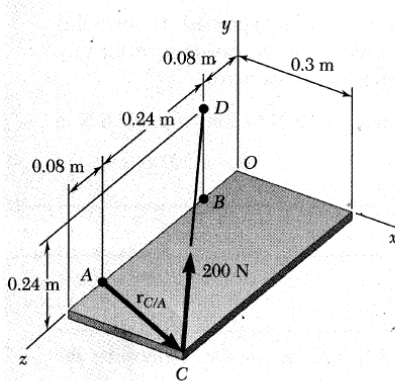


Fig. 1 The moment  $\mathbf{M}_A$  is determined from position vector  $\mathbf{r}_{C/A}$  and force vector  $\mathbf{F}$ .

where  $\mathbf{r}_{C/A}$  is the vector from  $A$  to  $C$

$$\mathbf{r}_{C/A} = \overrightarrow{AC} = (0.3 \text{ m})\mathbf{i} + (0.08 \text{ m})\mathbf{k} \quad (2)$$

and  $\mathbf{F}$  is the 200-N force directed along  $CD$  (Fig. 1). Introducing the unit vector

$$\boldsymbol{\lambda} = \overrightarrow{CD}/CD,$$

you can express  $\mathbf{F}$  as

$$\mathbf{F} = F\boldsymbol{\lambda} = (200 \text{ N}) \frac{\overrightarrow{CD}}{CD} \quad (3)$$

Resolving the vector  $\overrightarrow{CD}$  into rectangular components, you have

$$\overrightarrow{CD} = -(0.3 \text{ m})\mathbf{i} + (0.24 \text{ m})\mathbf{j} - (0.32 \text{ m})\mathbf{k} \quad CD = 0.50 \text{ m}$$

Substituting into (3) gives you

$$\begin{aligned} \mathbf{F} &= \frac{200 \text{ N}}{0.50 \text{ m}} [-(0.3 \text{ m})\mathbf{i} + (0.24 \text{ m})\mathbf{j} - (0.32 \text{ m})\mathbf{k}] \\ &= -(120 \text{ N})\mathbf{i} + (96 \text{ N})\mathbf{j} - (128 \text{ N})\mathbf{k} \end{aligned} \quad (4)$$

Substituting for  $\mathbf{r}_{C/A}$  and  $\mathbf{F}$  from (2) and (4) into (1) and recalling the relations in Eq. (3.7) of Sec. 3.1D, you obtain (Fig. 2)

$$\begin{aligned} \mathbf{M}_A &= \mathbf{r}_{C/A} \times \mathbf{F} = (0.3\mathbf{i} + 0.08\mathbf{k}) \times (-120\mathbf{i} + 96\mathbf{j} - 128\mathbf{k}) \\ &= (0.3)(96)\mathbf{k} + (0.3)(-128)(-\mathbf{j}) + (0.08)(-120)\mathbf{j} + (0.08)(96)(-\mathbf{i}) \\ \mathbf{M}_A &= -(7.68 \text{ N}\cdot\text{m})\mathbf{i} + (28.8 \text{ N}\cdot\text{m})\mathbf{j} + (28.8 \text{ N}\cdot\text{m})\mathbf{k} \end{aligned} \quad \blacktriangleleft$$

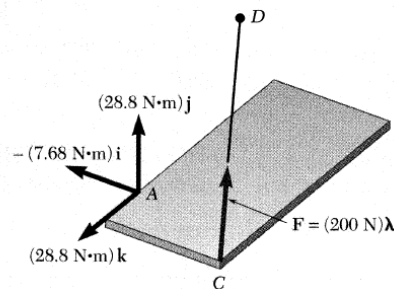


Fig. 2 Components of moment  $\mathbf{M}_A$  applied at  $A$ .

**Alternative Solution.** As indicated in Sec. 3.1F, you can also express the moment  $\mathbf{M}_A$  in the form of a determinant:

$$\begin{aligned} \mathbf{M}_A &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x_C - x_A & y_C - y_A & z_C - z_A \\ F_x & F_y & F_z \end{vmatrix} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0.3 & 0 & 0.08 \\ -120 & 96 & -128 \end{vmatrix} \\ \mathbf{M}_A &= -(7.68 \text{ N}\cdot\text{m})\mathbf{i} + (28.8 \text{ N}\cdot\text{m})\mathbf{j} + (28.8 \text{ N}\cdot\text{m})\mathbf{k} \end{aligned} \quad \blacktriangleleft$$

**REFLECT and THINK:** Two-dimensional problems often are solved easily using a scalar approach, but the versatility of a vector analysis is quite apparent in a three-dimensional problem such as this.